

VisualPen: A Physical Interface for natural human-computer interaction
 F. La Rosa, C. Costanzo, G. Iannizzotto

MOBILEHCI 03
 Physical Interaction (PI03)

VisualPen: A Physical Interface for natural human-computer interaction

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VisualPen

- It replaces keyboard and mouse:
 - write
 - draw
 - and also to point, select (click), drag&drop and double click.

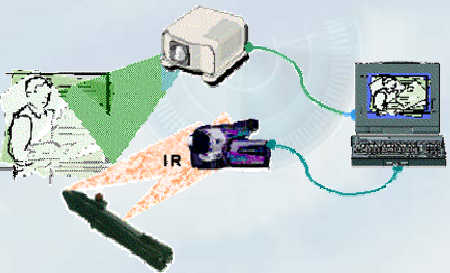



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VisualPen





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VisualPen

- The system can be operated from a wide range of distances
 - Desk
 - Board
- And, due to IR light, with all lightning conditions.



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VirtualBoard*: Gesture Recognition

- Bare Hand HCI
- writing and drawing is not very natural

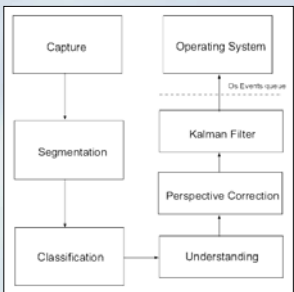
*C. Costanzo, G. Iannizzotto, and F. La Rosa - Virtualboard: Real-time visual gesture recognition for natural human-computer interaction. - In Proc. of the IEEE IPDPS'03, Nice, France, 2003.

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VisualPen: The algorithm



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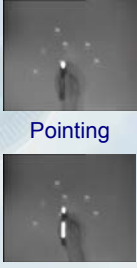
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VisualPen: The algorithm

Capture:

- Graylevel camera
- Resolution 320x240
- Two IR leds.



Pointing

Click event

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VisualPen: The algorithm

Segmentation:

- Thresholding
- Connected components search



Pointing

Click Event

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VisualPen: The algorithm

Classification and Understanding:

- Number of active leds in the same frame
- Shape analysis

$$M_{ij} = \left(\sum_x \sum_y a^{ij}(x, y) \right)$$

$$r_i = \left(\frac{M_{ij}}{M_{ij}} \right)$$

$$w_i = \left(\frac{M_{ij}}{M_{ij}} \right)$$

$$inter_{ij} = \left(\frac{M_{ij}}{M_{ij}} \right)$$

$$a_i = M_{ij} + inter_{ij}$$

$$b_i = M_{ij} + inter_{ij}$$

$$c_i = M_{ij} + inter_{ij}$$

$$square = \sqrt{(a_i^2 + b_i^2 + c_i^2)}$$

$$\theta = \arctan \frac{b_i}{a_i}$$

$$ca = \cos \theta$$

$$sa = \sin \theta$$

$$rotultra = ca^2 * M_{ij} + 2 * ca * sa * M_{ij} + sa^2 * M_{ij}$$

$$rotultra = sa^2 * M_{ij} + 2 * ca * sa * M_{ij} + ca^2 * M_{ij}$$

$$length = 4 * \sqrt{rotultra + inter_{ij}}$$

$$width = 4 * \sqrt{rotultra + inter_{ij}}$$

$$factor = \frac{length}{width}$$

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VisualPen: The algorithm

Perspective Correction:

- Different resolution between camera and multimedia video projector
- Not orthogonal (Trapezoidal distortion)



Desk

Board

$$x = \bar{X} * factor_x - offset_x$$

$$y = \bar{Y} * factor_y - offset_y$$

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Kalman Filtering:

- Filter noise
- Increase accuracy
- Smooth the motion




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Performances

- Several environments
- Accuracy and repeatability
- Different lighting conditions
- Ground-truth reference
- Standard deviation of error



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Performances

- Free hand
- Error less than 3 pixel




Horizontal straight line

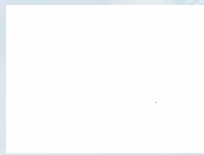
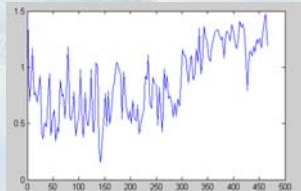
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Performances

- Free hand
- Error less than 1.5 pixel
- Uncertainty of the users in the second half of the abscissas

Arc of ellipse

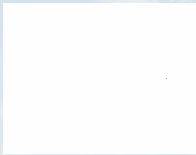
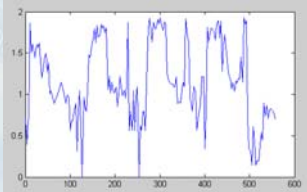
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Performances

- Free hand, pen constrained to slide on a fixed guide
- Intrinsic error oscillates around 1 pixel

Horizontal straight line

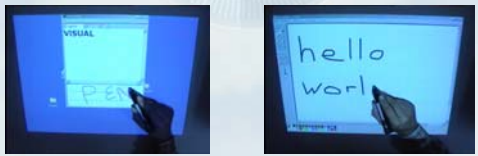
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Performances

- Error due to the different resolution of acquired and projected images
- Sub-pixel accuracy – computationally intensive
- Negligible for normal use



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Conclusions and future work

- Easy, natural input device
- Insensitive to lighting
- Low computational complexity
- Accurate
- Collaborative work sessions
- Interaction with Virtual and Augmented reality
- Porting to PDA devices

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